

Freehand System for Antenna Diagnosis Based on Amplitude-Only Data

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Abstract—This article presents a portable system for freehand antenna diagnosis and characterization based on amplitude-only data. The amplitude-only samples are acquired by moving a handheld probe, which is tracked by a motion capture system, in front of the antenna under test (AUT) aperture. The acquired measurements are processed using the phaseless sources reconstruction method to compute an equivalent current distribution on the AUT aperture. Finally, the radiation pattern of the AUT can be obtained by evaluating the corresponding radiation integrals. Unlike previous work, the use of amplitude-only data avoids the need of a phase reference, paving the way to the diagnosis and characterization of antennas under operational conditions. This fact, together with the handheld capabilities, makes the system very convenient for measurements of already deployed and onboard antennas. Moreover, these amplitude-only acquisitions also simplify the required hardware. The system has been validated through measurements in a wide frequency range from *Ka*-band up to 300 GHz. Despite that one cannot expect the same degree of accuracy that can be achieved under laboratory conditions (including an anechoic environment and highly accurate positioners), the system shows excellent capabilities to detect malfunctions, such as wrong amplitude/phase distributions, as well as a fair estimation of the far field.

Index Terms—Amplitude-only, antenna diagnosis, antenna measurements, equivalent currents, freehand, millimeter-wave (mm-wave) antenna, phaseless, power-meter, sources reconstruction method.

I. INTRODUCTION

ANTENNA diagnosis enables to assess the correct operation of this element. In this context, several techniques have been proposed to directly detect faulty elements of an array [1], [2] or to retrieve an equivalent currents distribution [3]–[5] providing more low-level information (e.g., the amplitude and phase of the elements of an array).

Usually, antenna diagnosis systems require mechanical positioners to ensure reliable sampling of the field radiated by the antenna under test (AUT). Nonetheless, recent advances demonstrated the feasibility of using freehand systems for antenna diagnosis based on a full acquisition (amplitude and phase) of the field radiated by the AUT [6], [7]. These systems, which can be fastly deployed, avoid the need of using mechanical structures to move the probe antenna. This offers great flexibility since the measurements are acquired at arbitrary positions as the operator of the system moves the handheld probe in front of the AUT aperture without the need of physical constraints. This freehand approach is particularly useful for assessing the performance of millimeter-wave (mm-wave) antennas and beyond because, at those frequencies, the probe antennas are lightweight and the reflections with the operator are limited. In addition, this method becomes particularly useful in those situations in which mechanical structures cannot be easily deployed as, for example, when analyzing onboard antennas.

In the framework of antenna diagnosis, the use of amplitude-only data is of great interest due to multiple reasons [8, Ch. 6]. First, the use of flexible cables to guarantee the same phase reference is not always possible (e.g., antennas under operational conditions). Second, amplitude-only acquisitions are significantly less demanding than full acquisitions in terms of hardware and, therefore, the overall cost of the measurement equipment is reduced. Third, despite the continuous development of technology, the acquisition of phase information at high frequencies (e.g., sub-mm-wave band) is challenging as cable bending before frequency multiplication can have a significant impact on the phase results and, moreover,

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equipment is not always commercially available beyond the sub-mm-wave band.

Different phase retrieval schemes have been proposed for phaseless antenna diagnosis. On the one hand, interferometric techniques are based on mixing the measured signal with a reference signal whose radiated fields are well-known [9]–[11]. On the other hand, phase information can also be retrieved using different probes [12]–[14], which encodes the phase information by means of providing the output of several linear combinations of the field at different points or by using multiple acquisition surfaces [15]–[19].

In this article, a freehand antenna diagnosis system based on amplitude-only data is presented. In order to reduce the hardware complexity of the system, a phase retrieval scheme based on acquisitions at multiple surfaces is adopted. In particular, a modified version of the source reconstruction method (SRM) [3], phaseless SRM (pSRM) [20], is used in this article. It is worthwhile to note that this phaseless diagnosis approach has been successfully tested for arbitrary acquisitions based on a drone-mounted probe [21]. However, in contrast to that system, in which the drone can be controlled to perform a given acquisition grid, which could suffer from deviations yielding the arbitrary points, a freehand system cannot rely on an operator being able to move the hand to very specific points even with a large tolerance. Instead of that, some extra flexibility must be provided so that the samples can be continuously acquired during the movements of the operator in order to increase the available information. However, the system must also be able to avoid oversampled areas due to the operator moving slowly (or even staying steady for a short time). Moreover, in contrast to [21], where a GPS-based system was used to track the position, an indoor system with sub-mm positioning accuracy must be used to acquire the positions of the probe.

It should be noted that the proposed system, due to its freehand nature, is not expected to reach the accuracy of conventional antenna measurement ranges. Nonetheless, it enables fast antenna diagnosis and characterization with a good accuracy and with enormous flexibility due to its ease of deployment. These features make the system of great interest as the need of high-capacity communications is driving the use of mm-wave and sub-mm-wave frequencies [22]–[26].

This article is organized as follows. First, the system architecture and the antenna diagnosis and characterization method are discussed in Section II. Second, the performance of the proposed system across multiple frequency bands is assessed in Section III. Finally, the conclusions are drawn in Section IV.

II. DESCRIPTION OF THE SYSTEM

In Sections II-A and II-B, the architecture of the system is presented and the method to perform phaseless freehand antenna diagnosis and characterization is discussed.

A. System Architecture

The system architecture shares the working principle of the freehand system presented in [7]. Thus, it shares its advantages regarding movements without mechanical constraints and quick deployability, but it is modified to consider

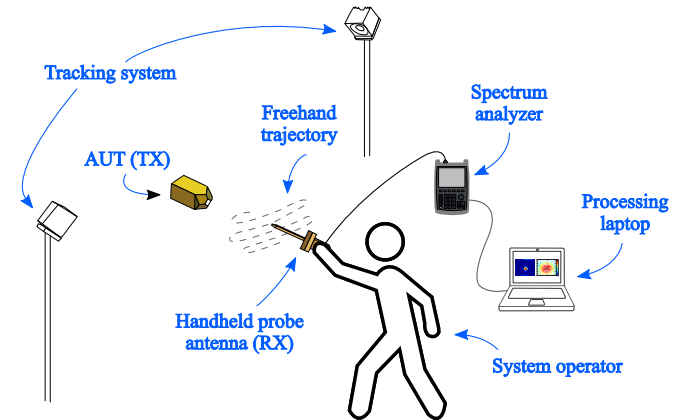


Fig. 1. Scheme of the proposed system.

amplitude-only acquisitions. Thus, the vector network analyzer (VNA) connections are removed yielding a setup in which the AUT and the probe antenna are not physically connected. In particular, the former antenna is connected to a power meter or equivalent system with capabilities to measure the power (or amplitude) of the radiated field. For example, a spectrum analyzer is also a good candidate for these acquisitions.

A scheme of the proposed system, in which the operator is moving the handheld probe antenna in front of the AUT aperture, is shown in Fig. 1. In a similar way to [7], the system comprises four subsystems.

- 1) *Probe Antenna*: A handheld probe antenna that is moved by the operator of the system in front of the AUT aperture.
- 2) *Amplitude Acquisition Subsystem*: A power detector or a spectrum analyzer to measure the amplitude of the near field radiated by the AUT.
- 3) *Positioning Subsystem*: It is necessary to accurately know where each near-field acquisition was performed in order to feed the processing algorithm used to retrieve the diagnosis and characterization of the AUT. In particular, in this implementation, an optical tracking system with an accuracy in the order of $100 \mu\text{m}$ was used [27].
- 4) *Processing Subsystem*: It is in charge of triggering amplitude and position acquisitions and processing the obtained data to perform the diagnosis of the AUT and to retrieve its radiation pattern.

B. Antenna Diagnosis and Characterization Technique

The SRM [3], which is based on the electromagnetic equivalence principle [28], computes equivalent electric and magnetic current distributions on a surface enclosing the AUT from acquisitions of its radiated field. These current distributions are computed so that the field radiated by the AUT outside the enclosing surface is equal to that radiated by the equivalent current distribution. It is computed by solving the linear system of integral equations that relate the field components to the equivalent currents recast into a matrix [3].

As the proposed system acquires amplitude-only data, it is necessary to include a phase retrieval method to overcome the lack of phase information. As previously introduced,

a modified version of the SRM, pSRM [20], is used in this article in order to reduce the hardware complexity of the proposed system. This technique relies on computing an equivalent currents distribution from the near-field amplitude measurements acquired from at least two *independent* acquisitions. The goal of these independent phaseless acquisitions is to provide enough information so that the phase of the field can be found from amplitude-only data. In particular, the acquisition surfaces are set to macroscopically resemble two independent planar acquisitions as it will be discussed in Section II-C.

Since only phaseless data is available, the system of equations has to be reformulated to relate the amplitude of the measured field with the one radiated by the equivalent current distribution. In contrast to the conventional SRM, this problem is not linear. It is worthwhile to note that, if the reconstruction domain is a planar surface, usually the AUT aperture, then only the equivalent magnetic currents are required [29]. This yields to the following nonlinear system of equations, which can be solved using a nonlinear minimization method such as Levenberg–Marquardt solver [30]:

$$\left\| \overline{\overline{A}} \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_N \end{bmatrix} \right\|^2 = \left\| \begin{bmatrix} E_1 \\ E_2 \\ \vdots \\ E_M \end{bmatrix} \right\|^2 \quad (1)$$

where b_n is the weight of the n th basis function and E_m is the field sample at the m th acquisition position. The matrix $\overline{\overline{A}}$ has dimensions $M \times N$, where N is the number of basis functions and M is the number of considered NF samples. The elements at row m and column n of the matrix $\overline{\overline{A}}$ relate the field at the m th position radiated by the n th basis function by means of the corresponding evaluation of Green's function [20]. Once the equivalent currents distribution is computed, the far-field radiation pattern of the AUT can be obtained by means of the corresponding radiation integrals [28], which effectively enable to implement a near-field to far-field (NF-FF) transformation.

C. Acquisition Method

One of the challenges of the proposed system comes from the freehand movement performed by the operator while scanning the AUT, which, at the same time, confers the system a great flexibility, as no mechanical guiding or supporting structures are required.

This nonregular movement, together with a continuous acquisition, yields a nonuniform sampling distribution, which may result in an inaccurate solution of (1) due to the lack of balance of the samples per surface unit. In order to prevent anomalous solutions, a strategy to balance the distribution of the acquisitions has to be adopted. In particular, a strategy similar to the one presented in [7] adapted to the constraints imposed by the lack of phase measurements has been employed.

A general scheme to illustrate the sampling balance strategy is shown in Fig. 2, where the AUT and two different acquisition volumes, S_1 and S_2 , can be observed. It should be noted

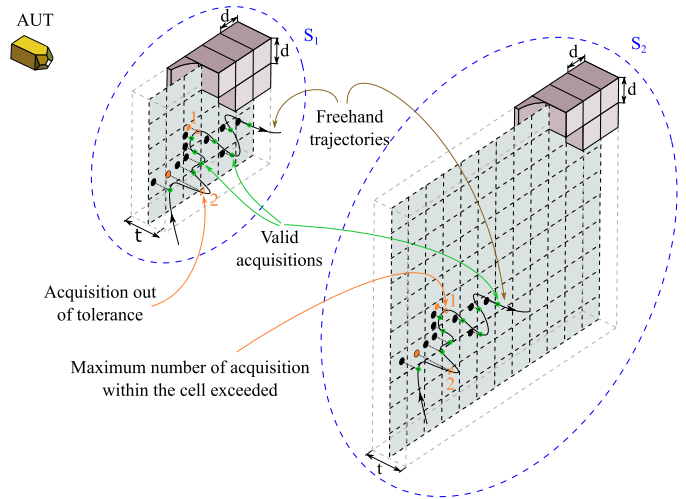


Fig. 2. Scheme of acquisition balance strategy to mitigate the effect of an unbalanced sampling distribution.

that, as S_1 is closer to the AUT than S_2 , a reduced scan has to be performed in S_1 when compared to S_2 . As it can be seen, each acquisition volume is made of cubic cells of size $d \times d \times t$ built around a virtual reference surface. Then, establishing a maximum number of acquisitions per cell, P , enables a procedure to mitigate the nonuniformities in sampling caused by the irregular freehand movements of the handheld probe. For example, if in a given area, the operator moves the probe slowly, then more acquisitions would be acquired in that area, which would result in a highly unbalanced sampling distribution if this strategy were not implemented. In particular, in Fig. 2, the maximum number of acquisitions per cell was set to $P = 2$ (as can be seen, the acquisitions denoted with the number 1 and an orange circumference are discarded as, in those same cells, two previous samples were acquired).

It is important to note that these acquisition volumes are discretized in such a way that they macroscopically resemble two planar acquisitions. In particular, the value of d can be seen as the usual sampling step and the value of the height of the cubic cells, t , is a tolerance that allows the operator to move the probe in a comfortable way (it is not possible to perform a perfectly planar freehand scan) while ensuring that electrically large gaps between samples are avoided. If, at some point during the scan, the operator moves the probe outside the cells, the measurements acquired will be discarded (for example, the acquisitions denoted with the number 2 and an orange square in Fig. 2). It should be remarked that if $P > 1$, the effective sampling is greater than the one given by the size of the cuboids. Furthermore, in order to set an upper bound of the probe antenna movement during a field acquisition, the position of the probe is queried before and after each acquisition, and if the difference is higher than a frequency-dependent threshold (e.g., $\lambda/10$), the field sample is discarded. In addition, the attitude of the probe is also monitored to be aware of the field component which is being acquired, as well as to discard samples when any of the attitude angles of the probe antenna are greater than a threshold (in this case 5°) to mitigate possible inaccuracies of the positioning system [7], [31]. In addition, a visual aid is displayed in the

interface so that the operator knows the distance to the top and bottom of the cubic cells in order to move the probe antenna to a valid area. Finally, the distribution of the acquisition points, in terms of a number of samples per cell, is depicted in a 2-D image in the interface shown to the operator, and the amplitude of the acquired samples is also depicted in the interface of the system.

D. Acquisition Speed Considerations

The overall acquisition time required to complete an antenna characterization employing the proposed system depends on several factors.

The first one is common to all kinds of planar acquisition (or pseudoplanar, such as the one presented here). As explained previously, it is necessary to acquire amplitude samples of the field radiated by the AUT in at least two planes that provide enough information so that the phase of the field can be found from the amplitude-only measurements. In addition, each of those planes should be large enough to measure most of the energy radiated by the AUT. Usually, one of the planes is placed as close to the antenna as possible (e.g., to avoid reactive coupling), while the other one is placed far enough so that field retrieval can be performed, but paying attention so that the energy is not too spread to avoid a too large acquisition plane. All these facts, inherited from planar measurements, are summarized in [32]. Further details on recommended practices for near-field antenna measurements are also given in [33].

The second factor that affects the acquisition speed is specific to the proposed system and it is related to the freehand nature of the system and the acquisition method discussed in Section II-C. In particular, as previously explained, the size of the cells, in which each acquisition volume is discretized, is related to the working frequency of the AUT to ensure proper sampling of its radiated field while allowing the operator to move the probe in a comfortable way. As a consequence, the lower the working frequency of the AUT is, the greater would be the size of the cubic cells and, in particular, the larger would be the tolerance t . Thus, it becomes easier for the operator of the system to move the probe antenna within the acquisition volume. In contrast, at higher frequencies, the tolerance will be smaller and it would be more likely that the operator moves the probe temporarily outside the acquisition volume. As a result, the acquisitions performed during that period would be discarded, increasing the overall acquisition time. At this point, it should be noted that a skilled operator able to keep the probe antenna within the acquisition volume would have an advantage for faster scanning. Finally, it should be remarked that it is possible to speed up the acquisition process by increasing the tolerance t as long as the number of samples per cell grows, effectively increasing the sampling rate of the acquired field. Thus, the sample density would macroscopically remain the same. However, due to some inherent (microscopically) imbalance, it can still have an impact on the result. Consequently, a tradeoff between the acquisition speed and the accuracy of the results must be found.

III. VALIDATION OF THE SYSTEM

The performance of the proposed system was assessed through several measurements, at different frequency bands, conducted at the research facilities of the Signal Theory and Communications group of the University of Oviedo (TSC-UniOvi) and the Institute of Electronics, Microelectronics and Nanotechnology (IEMN) of the University of Lille-CNRS.

A. Measurements in *Ka*-Band

The first set of measurements is focused on checking the capabilities of the system by comparing different full acquisition schemes versus the proposed phaseless approach. This set of measurements was performed at *Ka*-band. The measurements were performed in the planar range of the University of Oviedo [34] using a VNA (Keysight PNA-X) and a conventional laptop to process the acquired data. The measurement setup is shown in Fig. 3(a). The probe antenna was an open-ended waveguide (OEWG) and the AUT was a two-horn antenna array with an interelement spacing of 2.1 cm.

First, a reference measurement using the conventional mechanical positioners of the planar range was performed. In particular, a total of 3135 measurements of the NF radiated by the AUT (both amplitude and phase) were acquired during 6173 s in a regular grid of 24.4×25.2 cm² with a 0.45λ step at 30 GHz at a distance of 10.1 cm from the AUT aperture. Afterward, the acquired data were processed using the SRM [3] in order to obtain an equivalent current distribution on the aperture of the AUT. These reference results are shown in Fig. 3(b) and (f) for the normalized amplitude and phase of the computed equivalent currents distribution, respectively. The UV representation of the retrieved radiation pattern is shown in Fig. 3(j).

Then, two measurements acquiring both the amplitude and phase of the NF radiated by the AUT were performed using the freehand system. Four reflective markers were attached to the probe antenna, which was tracked using four infrared cameras [27]. In both measurements, the size of the cubic cells used to balance the distribution of the acquisitions was set to $\lambda/2 \times \lambda/2 \times \lambda/2$ at 30 GHz, and the maximum number of acquisitions per cell was set to 5. The first measurement was conducted at an average distance of 4.9 cm from the AUT aperture, a total of 2278 samples were collected during 566 s, and the size of the scanning plane was 16×16 cm². The normalized amplitude of the acquired NF samples is shown in Fig. 3(e). The second measurement was conducted at an average distance of 7.1 cm from the AUT aperture, a total of 4091 samples were collected during 984 s, and the size of the scanning plane was 19.6×23.3 cm². The normalized amplitude of the acquired NF samples is represented in Fig. 3(i). The normalized amplitude and phase of the equivalent currents distribution computed with the SRM from the measurements gathered during the second scan, using both amplitude and phase, are shown in Fig. 3(c) and (g), respectively. The UV representation of the retrieved radiation pattern is shown in Fig. 3(k). As it can be observed, although

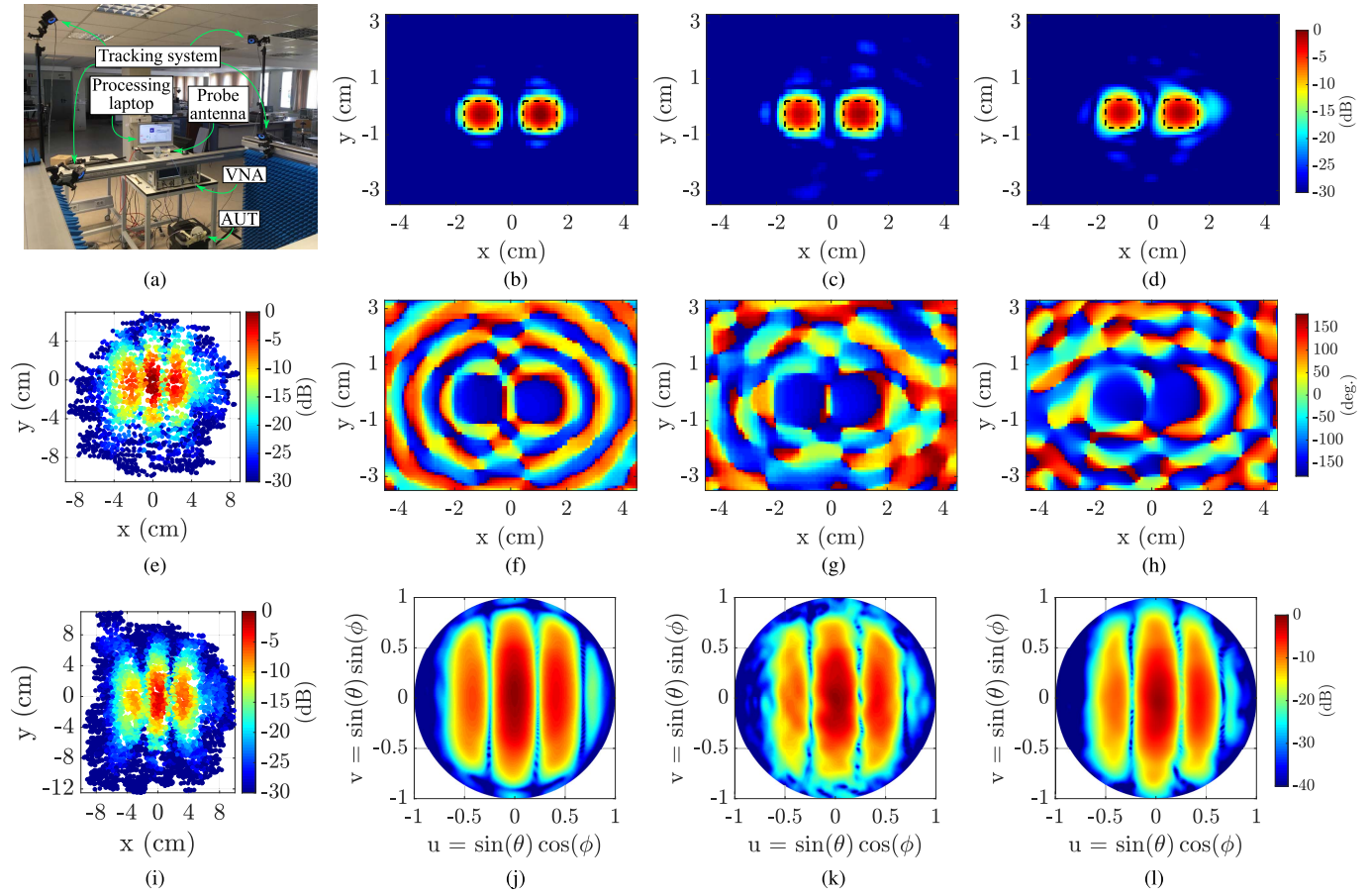


Fig. 3. (a) Setup for the Ka -band measurements. (b) Normalized amplitude and (f) phase of the computed equivalent currents distribution and (j) UV-representation of the retrieved radiation pattern obtained using the standard planar range. The same using (c), (g), and (k) amplitude and phase measurements acquired performing a freehand scan and (d), (h), and (l) using amplitude-only information and the proposed system. Normalized amplitude of the NF samples corresponding to (e) acquisition volume closest to the AUT aperture and (i) farthest one.

the obtained results are noisier than the reference ones due to the freehand nonuniform sampling, they accurately show the status of the antenna elements and its radiation pattern.

Finally, the performance of the proposed system was assessed by using only the amplitude information of the NF radiated by the AUT acquired during the two freehand acquisitions. The obtained equivalent currents distribution, retrieved using the pSRM, are shown in Fig. 3(d) and (h) for the normalized amplitude and phase, respectively. The UV representation of the retrieved radiation pattern is shown in Fig. 3(l). As it can be seen, the obtained results using amplitude-only data are slightly noisier than the reference ones in a similar fashion as when using both amplitude and phase data. This is a consequence of the freehand nature of the proposed system, which yields a nonuniform sampling distribution. Nonetheless, the results obtained using the proposed system are similar to the reference ones, showing the capability of the proposed system to provide accurate and fast diagnosis of an AUT. For a better comparison, the H-plane cut retrieved using the freehand approach with full acquisitions, as well as considering amplitude-only data, is shown in Fig. 4 together with the reference results obtained from the full acquisitions measured employing the conventional mechanical positioners

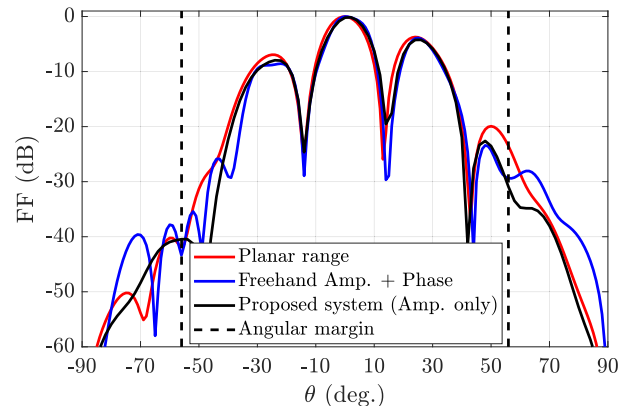


Fig. 4. H-plane cut ($\phi = 0^\circ$) retrieved using amplitude and phase measurements, as well as considering amplitude-only acquisitions. Reference results, obtained employing the standard positioners of the planar range and amplitude and phase acquisitions, are shown in red.

of the planar range. As it can be observed, the main and the secondary lobes within the valid angular margin are well-reconstructed using the proposed system, although the level of the secondary lobe at $\theta = 50^\circ$ is slightly lower than that of the reference pattern obtained with the planar range.

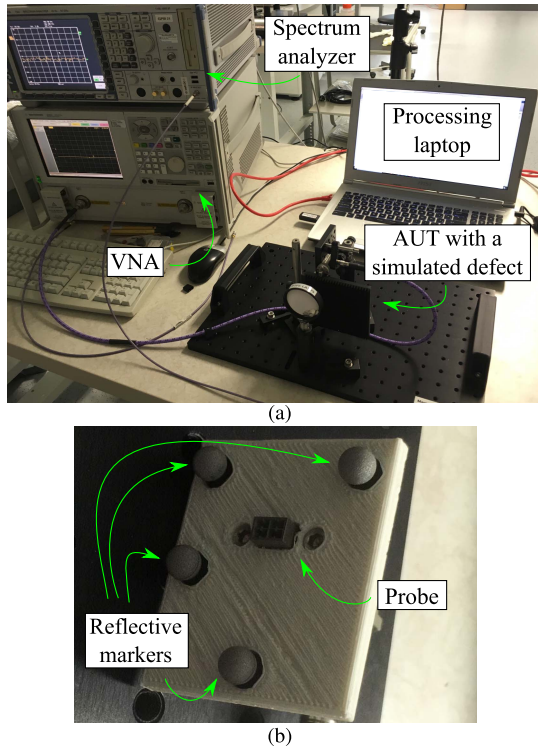


Fig. 5. (a) Setup and (b) probe antenna for V-band measurements.

B. Measurements in V-Band

The second set of measurements was performed at the facilities of the IEMN. In this case, the measurements were accomplished at 60 GHz using first a VNA (Keysight E8361A PNA) to obtain a reference measurement using both amplitude and phase information and a freehand trajectory. Afterward, the performance of the proposed system was evaluated by employing a spectrum analyzer (R&S FSU67) to acquire amplitude-only measurements, while the VNA was configured as a source to feed the AUT. The cubic cells used to balance the distribution of the acquisitions were of size $\lambda/2 \times \lambda/2 \times \lambda/2$ at 60 GHz, and the maximum number of acquisitions per cell was set to 5. Again, four infrared cameras were used to track the probe antenna [27]. The measurement setup is shown in Fig. 5(a), where it is possible to see the AUT: a PTFE plano-convex lens of 2.54 cm radius (5.1λ at 60 GHz) fed by an open double-ridged waveguide (DRWG) 2×2 array. Four reflective markers were attached to the probe antenna, which was another sample of the same DRWG 2×2 antenna used to feed the lens, to track it with the infrared cameras [see Fig. 5(b)].

As previously explained, the AUT [see Fig. 6(a)] was first characterized by acquiring both the amplitude and phase of its radiated NF. In particular, a total of 2351 samples were acquired at an average distance from the AUT of 11.1 cm during 505 s. The size of the scanned surface was $7.1 \times 7.5 \text{ cm}^2$. The normalized amplitude and phase of the computed equivalent currents distribution are shown in Fig. 6(b) and (c), respectively. As it can be seen, the region of the computed equivalent currents distribution, where the amplitude is high, matches the physical dimensions of the

TABLE I
SUMMARY OF THE ACQUISITIONS PERFORMED TO EVALUATE THE DIAGNOSIS CAPABILITIES OF THE PROPOSED SYSTEM

Defect	Measurement	# of samples	Avg. dist. to AUT (cm)	Time (s)	Scanned area (cm^2)
Al. strip	Amp. & Phase	2833	11.3	821	9.2×6.9
	Amp. only S1	4860	8.8	467	8.8×7.9
	Amp. only S2	5321	13.1	552	10.7×8.2
Al. patch	Amp. & Phase	3090	11.2	758	7.5×7.4
	Amp. only S1	3941	8.9	526	8.3×6.7
	Amp. only S2	4747	13.5	628	9.4×9.1

lens, whose edge is illustrated with a solid black line. Then, the AUT was characterized using the proposed system by acquiring amplitude-only NF measurements at two different average distances with the spectrum analyzer. The first set of 3444 NF samples was acquired at an average distance of 8.8 cm from the AUT aperture during 373 s. The size of the scanned area was $8.4 \times 7.1 \text{ cm}^2$. During the second acquisition, 4560 NF samples were acquired at an average distance of 15.3 cm from the AUT aperture. A total of 563 s were required to gather all the measurements and the size of the scanned area was $9.1 \times 7.7 \text{ cm}^2$. The normalized amplitude and phase of the equivalent currents distribution computed with the pSRM are shown in Fig. 6(d) and (e), respectively. As it can be observed, in a similar fashion as for the Ka-band measurements, although the results obtained with the proposed system are slightly noisier than those retrieved using phase information, they show good accuracy.

In addition, several tests were performed in order to assess the diagnosis capabilities of the system. For this purpose, two different defects were introduced to the AUT using aluminum foil. First, an aluminum strip crossing the lens was used [see Fig. 6(f)]. Once again, first, a reference measurement acquiring both the amplitude and phase of the NF radiated by the AUT was performed using the VNA and, afterward, the AUT was measured using the proposed system with a spectrum analyzer. A summary of the parameters of each scan can be found in the first three rows of Table I for the reference measurement and the two acquisition volumes scanned using the spectrum analyzer, respectively. The obtained results are shown in Fig. 6(g)–(j). As it can be seen, the normalized amplitude of the retrieved equivalent currents distribution vanishes where the aluminum strip was placed [see Fig. 6(g) and (i), for the reference measurement and using the proposed system, respectively]. Analogously, the phase of the equivalent currents distribution is disrupted where the aluminum strip was placed [see Fig. 6(h) and (j), for the reference measurement and using the proposed system, respectively].

For the second set of experiments, the aluminum strip was replaced by an aluminum patch, as shown in Fig. 6(k). As well as in the previous experiments, a reference measurement was performed and, afterward, the proposed system was tested. A summary of the parameters of each scan can be found in the last three rows of Table I for the reference measurement and the two acquisition volumes scanned using the spectrum analyzer, respectively.

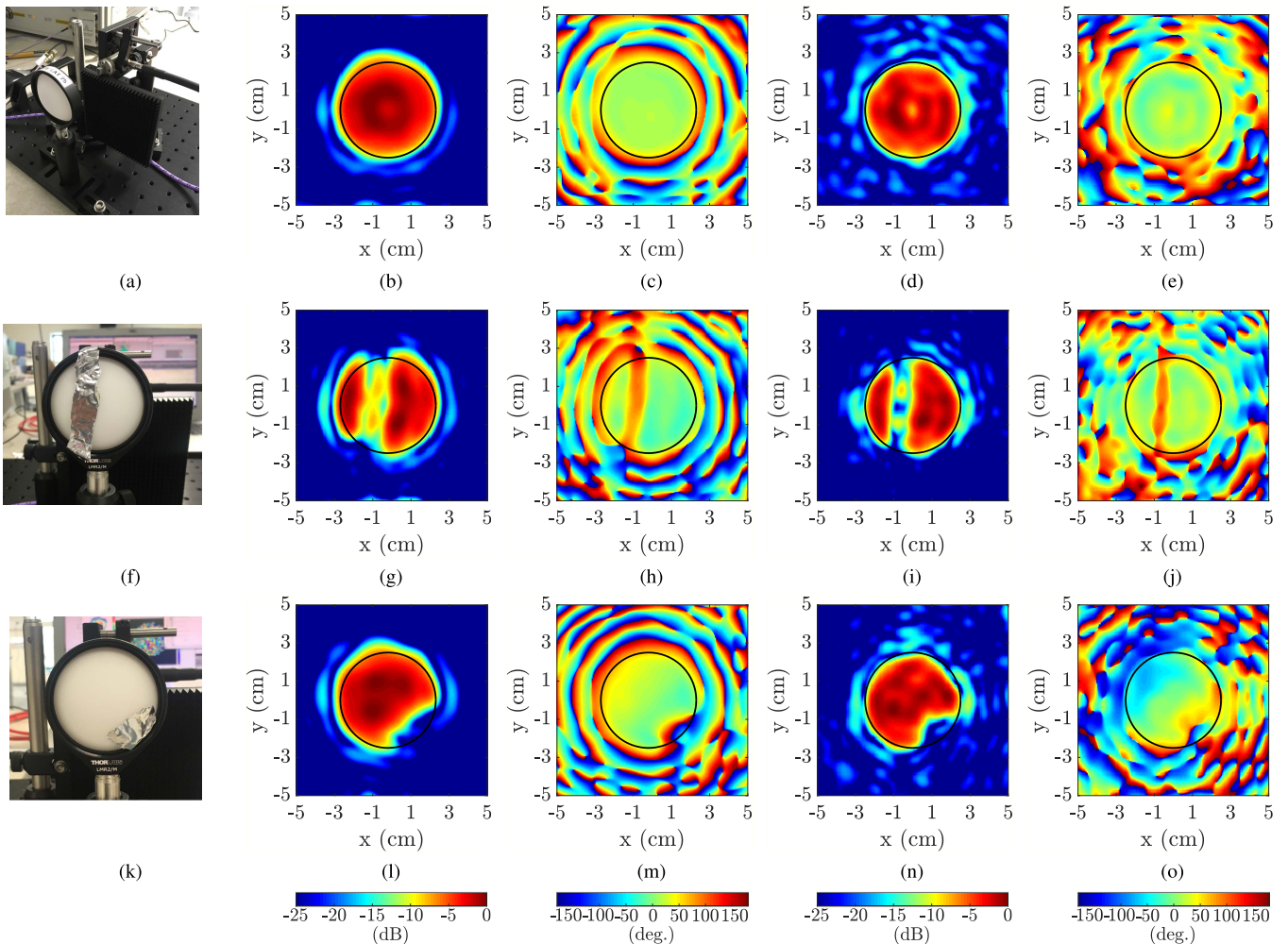


Fig. 6. (a) Image of the AUT; (b) normalized amplitude, and (c) phase of the computed equivalent currents distribution using amplitude and phase measurements acquired performing a freehand scan; (d) normalized amplitude and (e) phase of the computed equivalent currents distribution using amplitude-only information and the proposed system. (f) AUT with an aluminum strip to simulate an antenna malfunction; (g) normalized amplitude, and (h) phase of the computed equivalent currents distribution using amplitude and phase measurements acquired performing a freehand scan; (i) normalized amplitude and (j) phase of the computed equivalent currents distribution using amplitude-only information and the proposed system. (k) AUT with an aluminum patch to simulate an antenna malfunction; (l) normalized amplitude, and (m) phase of the computed equivalent currents distribution using amplitude and phase measurements acquired performing a freehand scan; (n) normalized amplitude and (o) phase of the computed equivalent currents distribution using amplitude-only information and the proposed system.

Once again, as expected, the normalized amplitude of the retrieved equivalent currents distribution vanishes where the aluminum patch was placed [see Fig. 6(l) and (n), for the reference measurement and using the proposed system, respectively]. The phase of the equivalent currents distribution is also disrupted where the aluminum patch was placed [see Fig. 6(m) and (o), for the reference measurement and using the proposed system, respectively]. These results demonstrate the capability of the proposed system to provide fast (in a matter of some minutes for an $81\lambda^2$ antenna) and accurate diagnosis of antenna malfunctions at the V-band.

C. Measurements at 300 GHz

Several measurements were performed at 300 GHz, pushing to the limits of the tracking system, to assess the performance of the proposed system. Due to the use of a sub-THz frequency and the difficulties of conducting accurate phase measurements at this frequency, in this case, only amplitude measurements were considered. These measurements were also performed at

the facilities of the IEMN. The measurement setup is shown in Fig. 7(a). In this case, the AUT was a conical horn antenna. The transmitted signal was generated using a signal generator, whose output signal was upconverted using a signal generator extension. On the receiving side, the probe antenna, in this case an OEWG shown in Fig. 7(b), was connected to a spectrum analyzer extension module, which was wired to the spectrum analyzer used for the amplitude-only measurements presented in Section III-B. The same tracking system as in the previous measurements, which comprises four infrared cameras, was employed. In this case, the size of the cubic cells used to balance the distribution of the acquisitions was set to $\lambda/2 \times \lambda/2 \times \lambda$ at 300 GHz and the maximum number of samples per cell was set to 5.

As in the previous amplitude-only measurements, amplitude samples were acquired within two different acquisition volumes. The main parameters of each scan are summarized in Table II. It should be noted that, as the size of the cubic cells used to balance the distribution of the acquisitions is

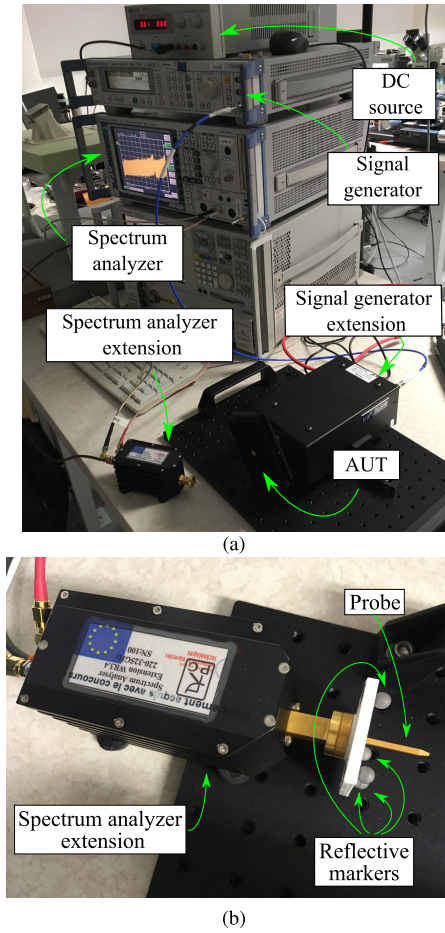


Fig. 7. (a) Measurement setup and (b) probe antenna for the 300 GHz measurements.

TABLE II
SUMMARY OF THE ACQUISITIONS PERFORMED TO MEASURE THE AUT AT 300 GHz

Measurement	# of samples	Avg. dist. to AUT (cm)	Time (s)	Scanned area (cm ²)
Amp. only S1	6020	4.7	1162	4.1 × 5.4
Amp. only S2	10314	7.6	2313	5.4 × 7.7

physically smaller than in previous measurements due to the higher working frequency, the time required to perform a scan grows as it is more difficult for the operator of the system to keep the probe within each acquisition volume. Nonetheless, the time required to scan the AUT with the proposed system is significantly less than that needed when using a conventional antenna measurement range.

The normalized amplitude of the field samples acquired within each acquisition volume is shown in Fig. 8(a) and (b).

The normalized amplitude and phase of the equivalent currents distribution computed using the pSRM employing the amplitude measurements acquired using the proposed system are shown in Fig. 9(a) and (b), respectively. As it can be observed, the area at which the normalized amplitude of the retrieved equivalent currents distribution is high corresponds to the AUT aperture, which is enclosed by a black dashed line in Fig. 9(a).

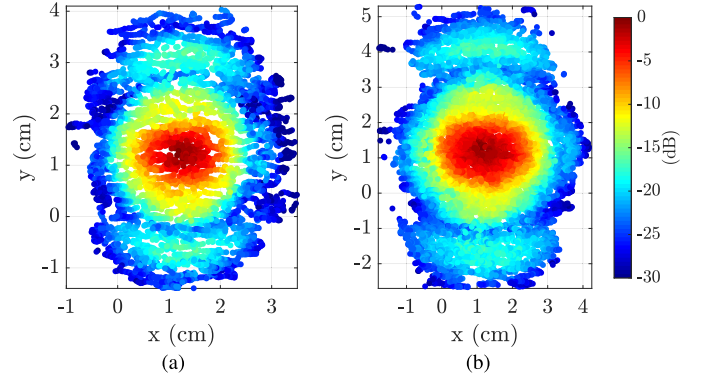


Fig. 8. Normalized amplitude of the acquired field samples within (a) acquisition volume closest to the AUT, S_1 , and (b) farthest one, S_2 .

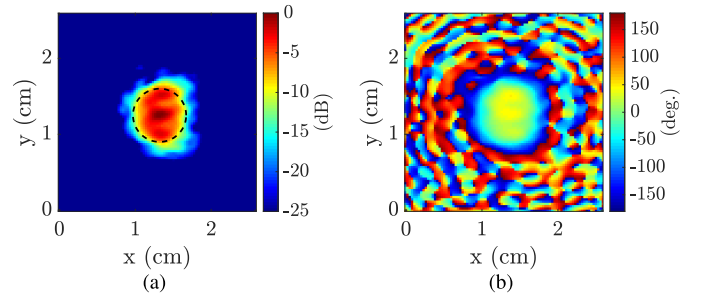


Fig. 9. (a) Normalized amplitude and (b) phase of the computed equivalent currents distribution of the AUT at 300 GHz.

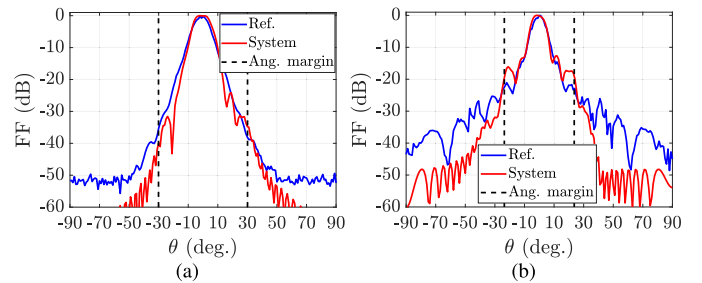


Fig. 10. (a) H-plane ($\phi = 0^\circ$) and (b) E-plane ($\phi = 90^\circ$) cuts of the retrieved far-field pattern of the AUT at 300 GHz.

The H-plane cut and the E-plane cut of the retrieved radiation pattern are shown in Fig. 10(a) and (b), respectively, along with the reference cuts obtained with the conventional antenna measurement range of the IEMN [35]. As it can be seen, in both cuts of the radiation pattern, the main lobe is well-estimated. In addition, the position of the secondary lobes in the E-plane cut within the angular margin of validity is also well-predicted, although the level of the secondary lobes of the pattern retrieved with the proposed system is slightly higher than in the reference pattern. Therefore, it can be concluded that using the proposed system, a good diagnosis and a fair characterization of antennas, even at sub-THz frequencies, can be performed in a fast and flexible manner.

IV. CONCLUSION

In this article, a portable system to perform freehand antenna diagnosis and characterization using amplitude-only data has been presented.

The system comprises a handheld probe antenna, a motion capture system to track the probe position and attitude, a power detector or a spectrum analyzer connected to the probe to measure the amplitude of the field radiated by the AUT, and a conventional laptop to trigger the measurements and process the acquired data. The handheld probe is moved by the operator of the system (who does not need to be trained) during the scan in front of the AUT aperture, while data acquisitions are triggered. To enable the freehand operation of the system, which confers great flexibility, a strategy to avoid highly unbalanced sample distributions and to ensure a proper sampling has been implemented. The resulting data, involving acquisitions from at least two acquisition volumes so that phase retrieval can be performed, is processed by employing the pSRM to estimate an equivalent currents distribution on the AUT aperture and, ultimately, to compute its radiation pattern by solving the corresponding radiation integrals.

The proposed system has been validated within a wide frequency range. In particular, the performance of the proposed system has been assessed in *Ka*-band, *V*-band, and at 300 GHz, showing good results according to the reference measurements obtained with conventional antenna measurement facilities and considering amplitude and phase samples (amplitude-only acquisitions in the case of the 300 GHz reference measurement). In this regard, it should be remarked that the system is not expected to reach a similar accuracy as the one obtained with traditional antenna measurement ranges, but to provide a portable and easy-to-deploy alternative for fast performance assessment of antennas. Among the possible applications of the system, it enables the quick performance evaluation of antennas in laboratory conditions or the characterization of already deployed and onboard antennas. Moreover, the use of amplitude-only data, which reduces the overall cost of the equipment, and the portability of the system enable the characterization of antennas under operational conditions as no synchronization is required between Tx and Rx antennas, which will be the subject of future work.

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